

CSC4200/5200 – COMPUTER NETWORKING

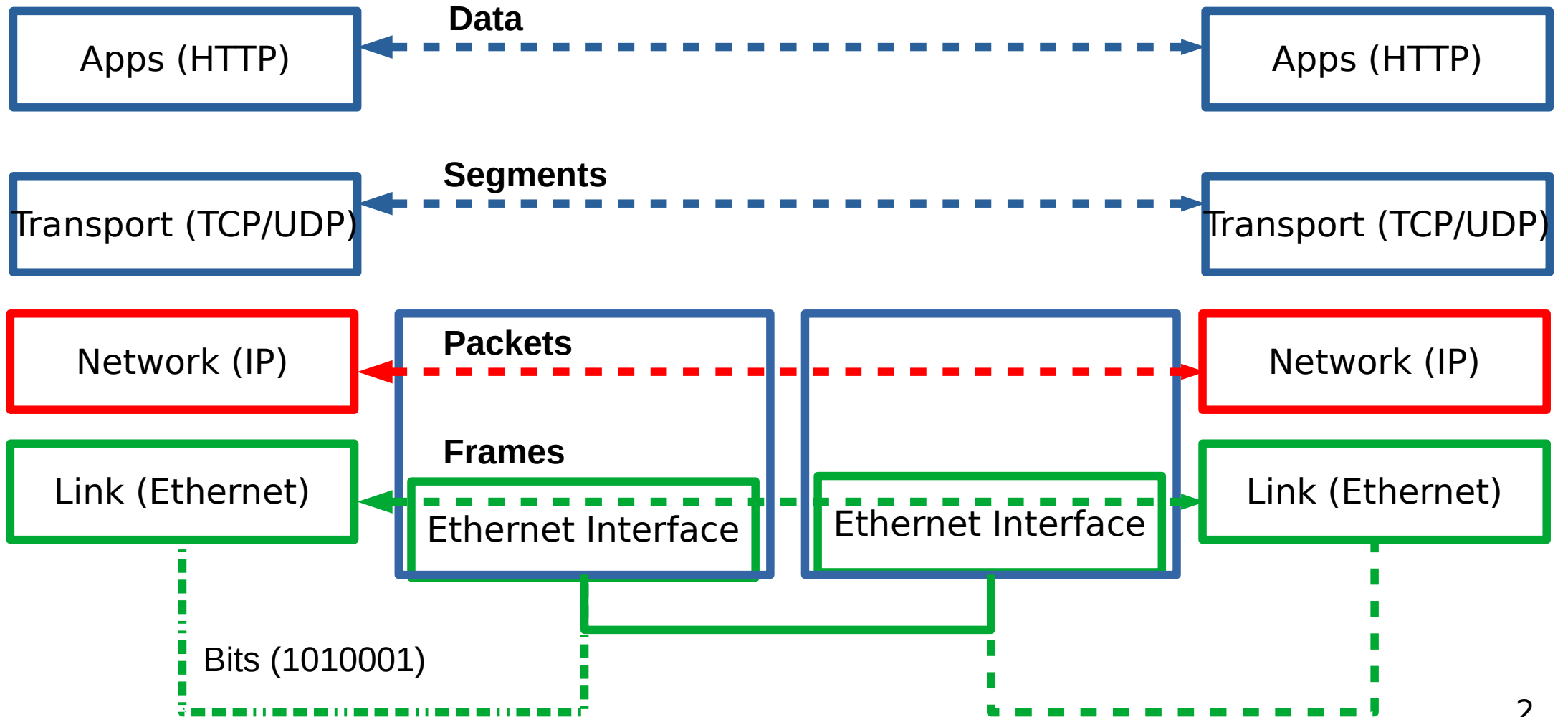
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ROUTING - CONTINUED

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Forwarding vs Routing

- Forwarding:
 - to select an output port based on destination address and routing table
 - **Local path**
- Routing:
 - process by which routing table is built
 - **End-to-end path**

SubnetNumber	SubnetMask	NextHop
128.96.34.0	255.255.255.128	Interface 0
128.96.34.128	255.255.255.128	Interface 1
128.96.33.0	255.255.255.0	R2

Routing = Navigation

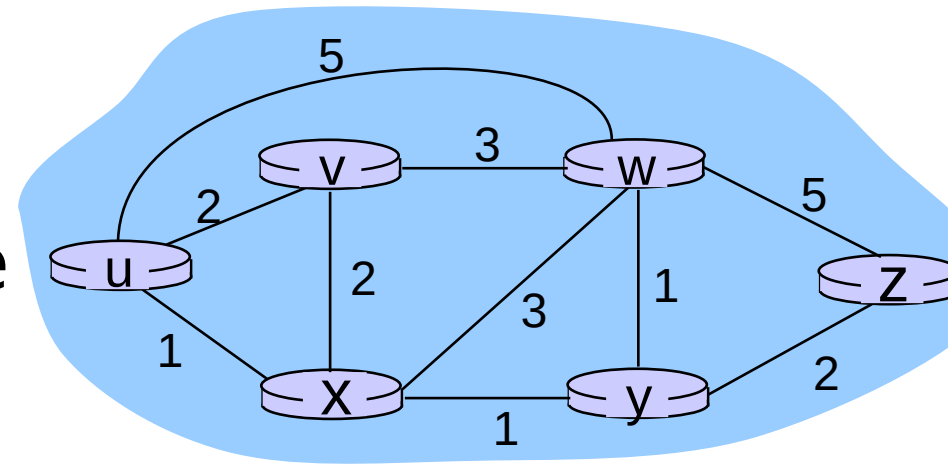
The screenshot shows a Google Maps interface with a route from Cookeville, Tennessee to the Geographical Center of the United States. The map displays three route options:

Route Description	Distance	Travel Time
via I-29 N and I-90 W Fastest route, the usual traffic ⚠️ Your destination is in a different time zone.	1,409 miles	20 hr 28 min
via I-90 W	1,422 miles	21 hr 18 min
via US-20 W and I-90 W	1,466 miles	21 hr 33 min

Below the route options, there is a section titled "Explore Geographical Center of Entire United States" with icons for Restaurants, Hotels, Gas stations, and Parking Lots.

Why bother?

- Quality of path affects performance
 - Longer path = more delay
- Balance path usage, avoid congested paths
- Deal with failures



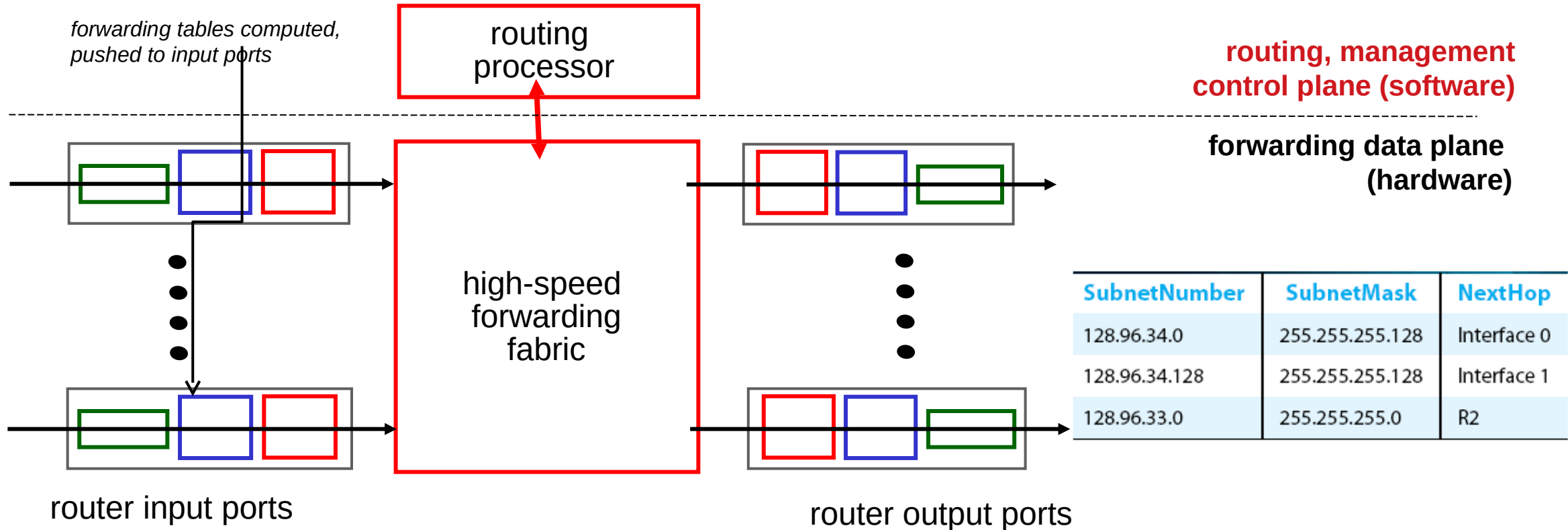
SubnetNumber	SubnetMask	NextHop
128.96.34.0	255.255.255.128	Interface 0
128.96.34.128	255.255.255.128	Interface 1
128.96.33.0	255.255.255.0	R2

Router architecture overview

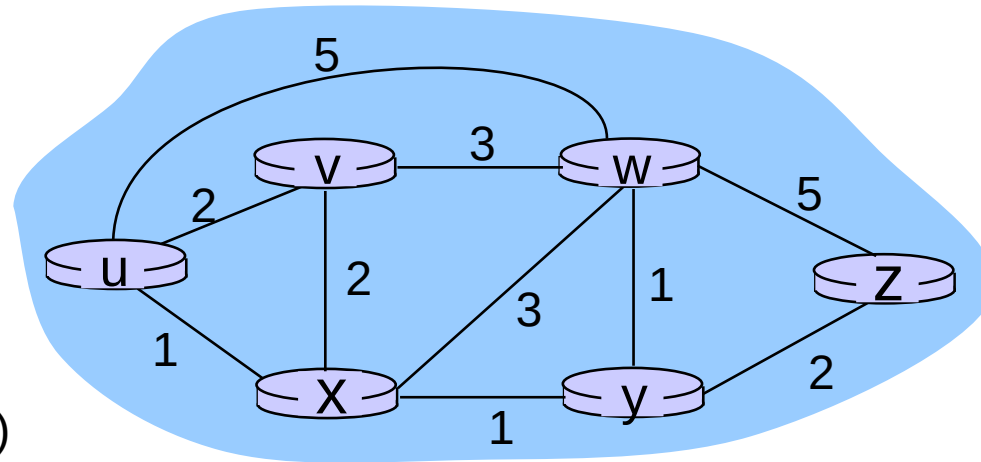
Two key router functions:

- run routing algorithms/protocol (RIP, OSPF, BGP)
- *forwarding* datagrams from incoming to outgoing link

Control Plane = routing
Vs
Data Plane = forwarding



Graph abstraction



graph: $G = (N,E)$

$N =$ set of routers = $\{ u, v, w, x, y, z \}$

$E =$ set of links = $\{ (u,v), (u,x), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z) \}$

X → Z

Cost $(x,v,w,z) = \text{cost}(x,v) + \text{cost}(v,w) + \text{cost}(w,z) = 10$

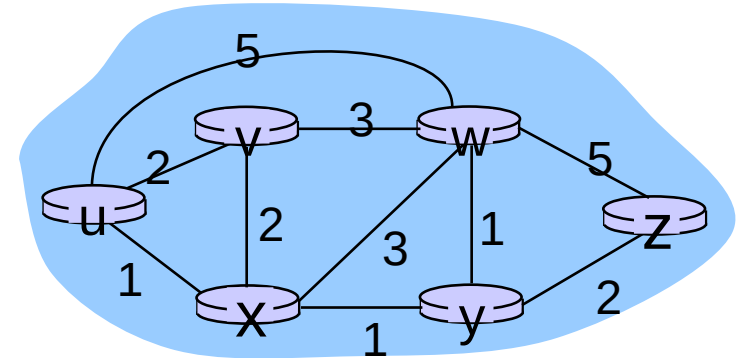
Cost $(x,w,z) = \text{cost}(x,w) + \text{cost}(w,z) = 8$

Cost $(x,y,z) = ?$

Objective → find the lowest cost path between **all** nodes

Dijkstra's Shortest-Path Algorithm

- Given a graph (network) with link costs
- Find the lowest cost paths to all nodes
- Iterative
 - After n iterations, you will find least cost path to n nodes
- S = Least cost paths already known, initially source node $\{U\}$
- $D(v)$: current cost of path from source(U) to node V
 - Initially, $D(v) = c(u,v)$ for all nodes v adjacent to u
 - $D(v) = \infty$ for all other nodes
 - Update $D(v)$ as we go



Dijkstra's Algorithm

1 **Initialization:**

2 $N' = \{u\}$

3 for all nodes v

4 if v adjacent to u

5 then $D(v) = c(u,v)$

6 else $D(v) = \infty$

7

8 **Loop**

9 find w not in N' such that $D(w)$ is a minimum

10 add w to N'

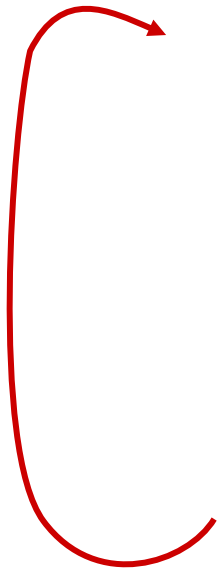
11 update $D(v)$ for all v adjacent to w and not in N' :

12 **$D(v) = \min(D(v), D(w) + c(w,v))$**

13 /* new cost to v is either old cost to v or known

14 shortest path cost to w plus cost from w to v */

15 **until all nodes in N'**

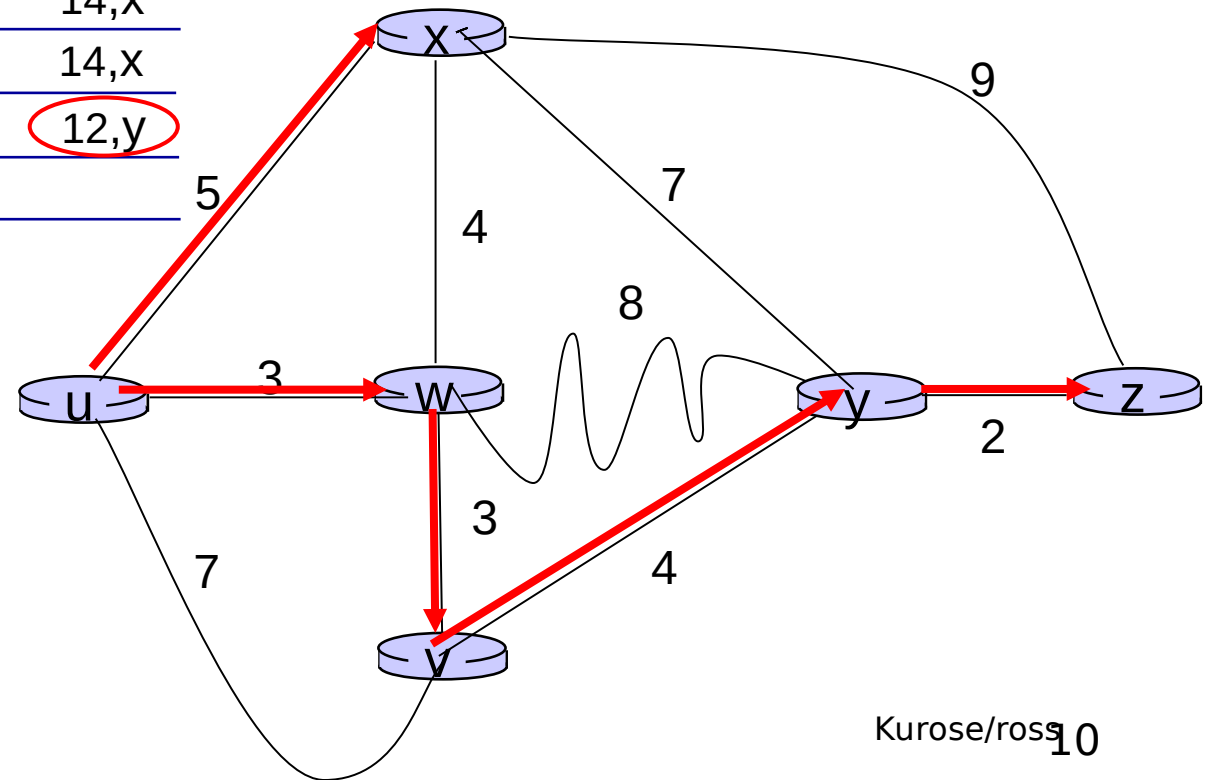


Dijkstra's algorithm: example

Step	N'	D(v) p(v)	D(w) p(w)	D(x) p(x)	D(y) p(y)	D(z) p(z)
0	u	7,u	3,u	5,u	∞	∞
1	uw	6,w		5,u	11,w	∞
2	uwx	6,w			11,w	14,x
3	uwxv				10,v	14,x
4	uwxvy					12,y
5	uwxvyz					

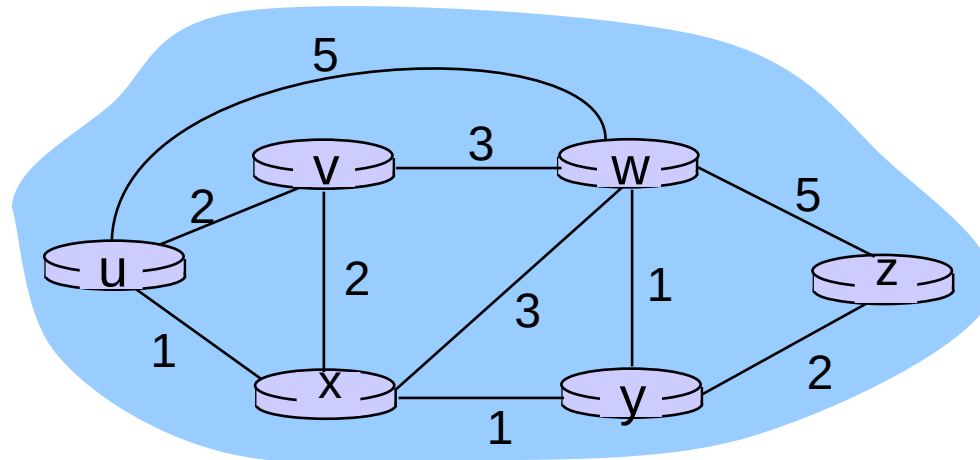
notes:

- ❖ construct shortest path tree by tracing predecessor nodes
- ❖ ties can exist (can be broken arbitrarily)



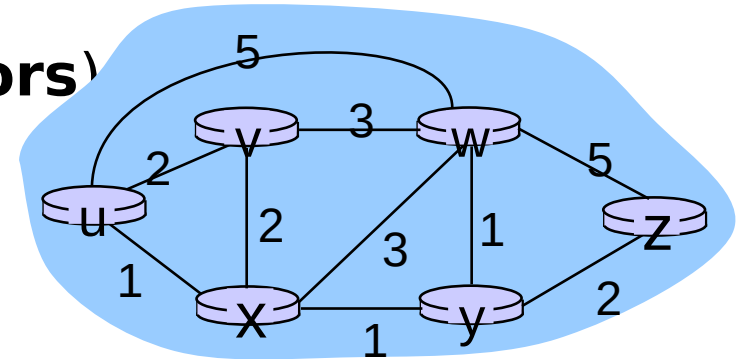
Dijkstra's algorithm: another example

Step	N'	$D(v), p(v)$	$D(w), p(w)$	$D(x), p(x)$	$D(y), p(y)$	$D(z), p(z)$
0	u	2, u	5, u	1, u	∞	∞
1	ux	2, u	4, x		2, x	∞
2	uxy	2, u	3, y			4, y
3	uxyv		3, y			4, y
4	uxyvw					4, y
5	uxyvwz					



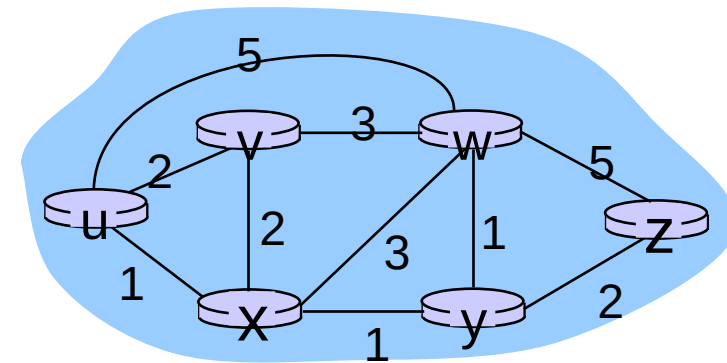
Dijsktra's → Link State Routing

- Each node keeps track of adjacent links (**neighbors**)
- Each router broadcasts it's state (**network map**)
- Each router runs Dijkstra's algorithm
(**finds the shortest path**)
- Each router has complete picture of the network
- Example: Open Shortest Path First (OSPF)

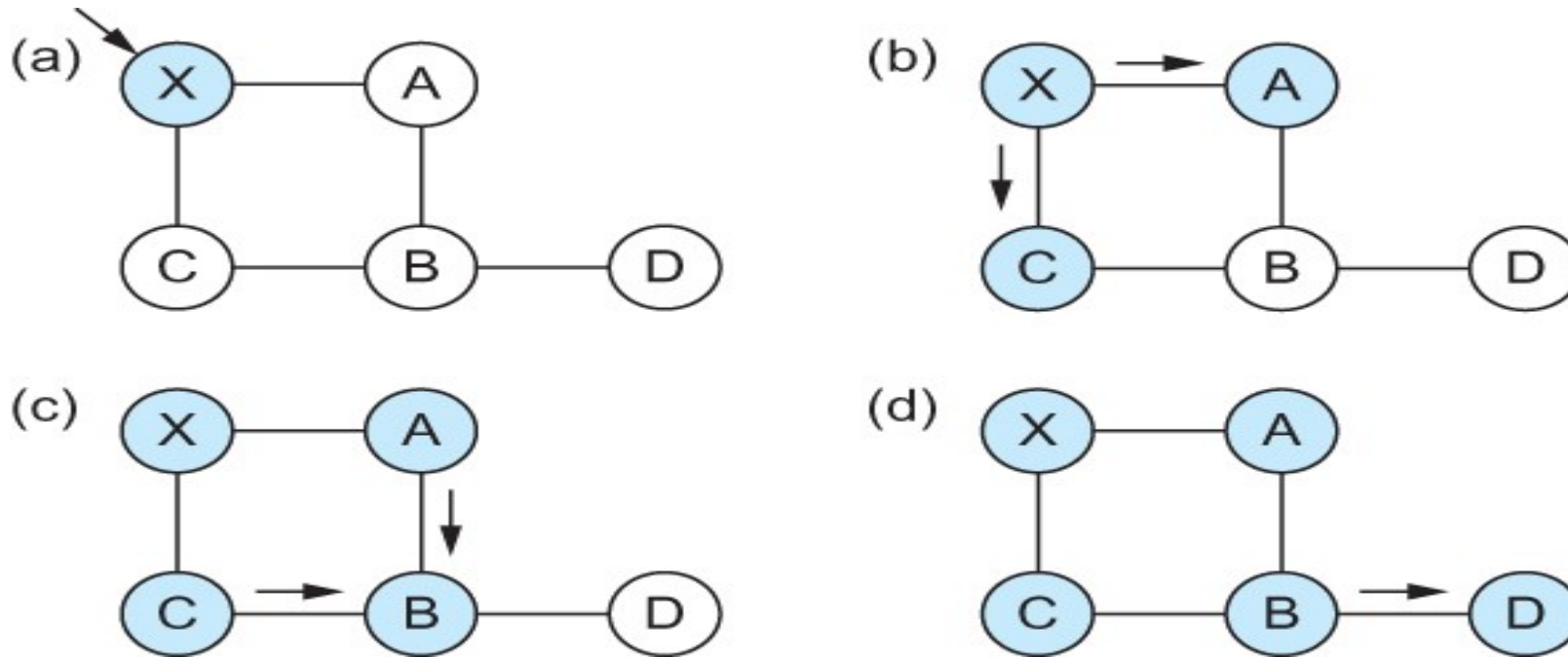


OSPF – Open Shortest Path First

- SPF – another name for Link State Routing
- Each node creates an update packet - link-state packet (LSP)
 - The ID of the node that created the LSP (U)
 - A list of directly connected neighbors and the cost of the link ((V, 2), (X, 1), **(W, 5)**)
 - A sequence number (1122)
 - A time to live for this packet (16)
- LSP → ({U}, {(V, 2), (X, 1), (W, 5)}, {1122}, {16})



OSPF - controlled flooding



Flooding of link-state packets. (a) LSP arrives at node X; (b) X floods LSP to A and C; (c) A and C flood LSP to B (but not X); (d) flooding is complete

Link State Routing – controlled flooding

- Flood when topology changes or link goes down
 - Detected by periodic hello messages
 - If message missed → link down
- Refresh and flood periodically
- Problems?
 - High computational cost
 - Reliable flooding may not be reliable

Tying it all together in the network layer

SRC	2.2.2.2
DST	5.5.5.5

Decapsulate IP packet

SRC	bbbb
DST	dddd
SRC	2.2.2.2
DST	5.5.5.5

L1H1
2.2.2.2
Ether: cccc

SRC	2.2.2.2
DST	5.5.5.5



DHCP server



ARP: WHO HAS 5.5.5.5?



Youtube
5.5.5.5
Ether: dddd

youtube: I do!
Ethernet address: dddd



Iface 1:
2.2.2.1
Ether: aaaa

Iface 2:
5.5.5.1
Ether: bbbb

SRC	2.2.2.2
DST	5.5.5.5

Routing Table

5.5.5.0/8	IF: 2
2.2.2.0/8	IF: 1

We are populating this!!!

Reading Assignment

- Network as a graph:
 - <https://book.systemsapproach.org/internetworking/routing.html#network-as-a-graph>
 - Approximately 5 minutes
- Link state:
 - <https://book.systemsapproach.org/internetworking/routing.html#link-state-ospf>
 - Approximately 20 minutes